





# STATISTICAL PHYSICS AND MACHINE LEARNING



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26-27 September, 2019, ETH Zurich Artificial Intelligence and the Scientific Method

# CO-RESPONSIBLE

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# Machine Learning (ML) Artificial Intelligence and the Scientific Method?

- → How is ML changing the scientific method?
- → Do we need scientific method to advance ML?

## ENGINEERING & SCIENCE

• ML mostly developed by engineering design process: Define an objective (e.g. to reach the best accuracy on ImageNet). Create a tool that reaches the objective.

Rank	Method	Top 1 Accuracy	Top 5 Accuracy	Number of params	Extra Training Data	Paper Title	Year	Paper	Code
1	FixResNeXt- 101 32x48d	86.4%	98.0%	829M	~	Fixing the train-test resolution discrepancy	2019		O

- → Deep learning is a revolutionary engineering progress.
- Scientific method aims to understand behaviour of existing world. Do we understand why FixResNeXt-101 works?
  - ⇒ Science/understanding of deep learning is in its infancy.
    Do we know more about black holes or deep learning?

# MORE QUESTIONS

- Do we need science/understanding? Isn't engineering enough, simply because "it works"?
- Some questions for which I think engineering is not enough:

For instance, there are many important questions regarding neural networks which are largely unanswered. There seem to be conflicting stories regarding the following issues:

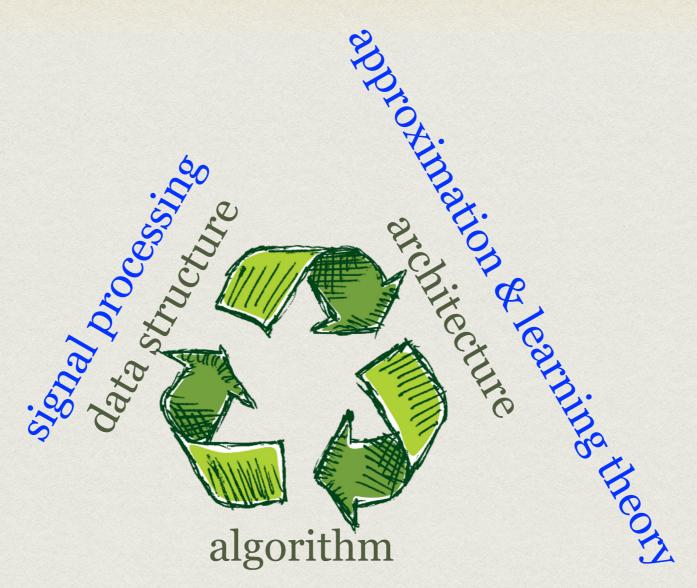
- Why don't heavily parameterized neural networks overfit the data?
- What is the effective number of parameters?
- Why doesn't backpropagation head for a poor local minima?

From "Reflections after refereeing papers for NIPS", Leo Breiman, 1995.

Still not answered!

#### TOWARDS THEORY OF DEEP LEARNING?

Inter-play of three ingredients



computer science, optimisation theory

See also: E. Mossel, Deep Learning Boot Camp in Simons Institute, Berkeley (June 2019).

# LONG-LASTING FRIENDSHIP BETWEEN MACHINE LEARNING AND STATISTICAL PHYSICS

#### STATISTICAL PHYSICS AND MACHINE LEARNING

13 M. MEZARD



Yann LeCun is with Levent Sagun and 3 others. August 30

Stéphane Mallat's tutorial at the "Statistical Physics and Machine Learning back Together" summer school in Cargese, Corsica.

There is a long history of theoretical physicists (particularly condensed matter physicists) bringing ideas and mathematical methods to machine learning, neural networks, probabilistic inference, SAT problems, etc.

In fact, the wave of interest in neural networks in the 1980s and early 1990s was in part caused by the connection between spin glasses and recurrent nets popularized by John Hopfield. While this caused some physicists to morph into neuroscientists and machine learners, most of them left the field when interest in neural networks wanted in the late 1990s

With the prevalence of deep learning and all the theoretical questions that surround it, physicists are coming back!

Many young physicists (and mathaticians) are now working on trying to explain why deep learning works so well. This summer school is for them.

We need to find ways to connect this emerging community with the ML/AI community. It's not easy because (1) papers submitted by physicists to ML conferences rarely make it because of a lack of qualified reviewers; (2) conference papers don't count in a physicist's CV.

http://cargese.krzakala.org

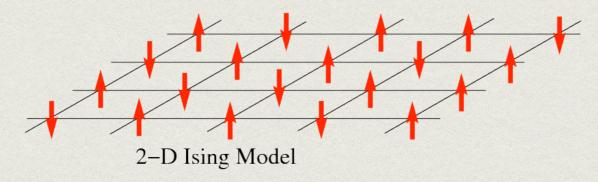


# Disordered Systems and Biological Organization

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16	J.J. HOPFIELD, D.W. TANK Collective computation with continuous variables.	155
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30	D. GEMAN, S. GEMAN Bayesian image analysis.	301

# MODELS

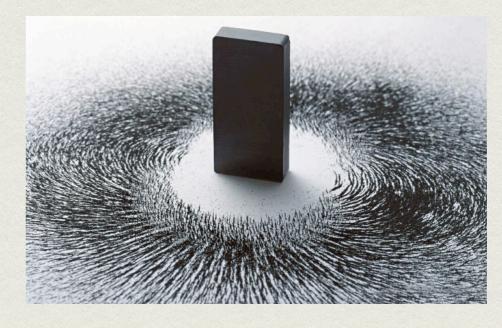
- In data science, models are used to fit the data (e.g. linear regression: Best straight line that captures the dependence of y on x?). In physics we could call those an "ansatz".
- In physics, models are the main tool for understanding.



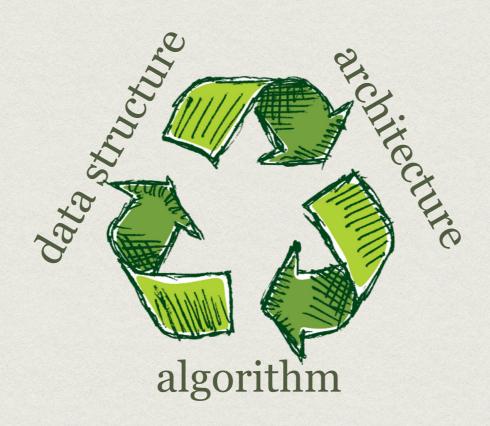
$$P(\lbrace S_i \rbrace_{i=1,...,N}) = \frac{e^{-\beta \mathcal{H}}}{Z}$$

$$\mathcal{H} = -J \sum_{(ij) \in \mathbb{E}} S_i S_j$$

#### magnetism of materials



#### WHAT TO MODEL IN DEEP LEARNING?



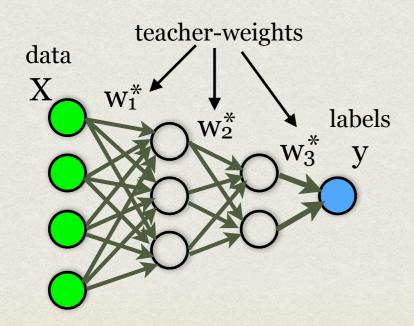
We aim to reproduce the salient behaviours of the real system.

Iterative process of improving the model.

# WHEN CAN A NEURAL NETWORK LEARN A TEACHER-NEURAL NETWORK?

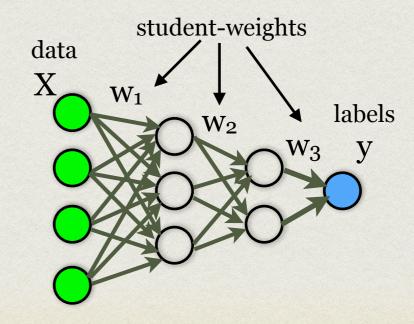
#### Teacher-network

- Generates data X, n samples of p dimensional data, e.g. random input vectors.
- Generates weights w\*, e.g. iid random.
- Generates labels y.



#### Student-network

- Observes X, y, the architecture of the network.
- How does the best achievable generalisation error depend on the number of samples n?



Yoshua Bengio at France in AI'18: On challenges of deep learning towards AI.



#### Alien Language Understanding: a Thought Experiment

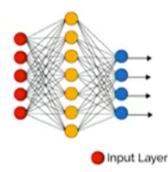
- Imagine yourself approaching another planet and observing the bits of information exchanged by aliens communicating with each other
- Unlike on Earth, their communication channel is noisy, but like on Earth, bandwidth is expensive → the best way to communicate is to maximally compress the messages, which leads to sequences of random bits being actually exchanged.

If we only observe the compressed messages, there is no way we can ever



#### Sanjeev Arora at ICML'18: Tutorial on theory of deep learning.

# Overparametrization may help optimization: folklore experiment e.g [Livni et al'14]



Generate labeled data by feeding random input vectors Into depth 2 net with hidden layer of size n

Still no theorem explaining this...

Input Layer

Difticult to train a new net using this labeled data with same # of hidden nodes

Much easier to train a new net with bigger hidden layer!

facebook



7/10/2018

Theoretically understanding deep learning

#### TEACHER-STUDENT PERCEPTRON

Gardner, Derrida'89, Gyorgyi'90

J. Phys. A: Math. Gen. 22 (1989) 1983-1994. Printed in the UK

1989

#### Model B in:

## Three unfinished works on the optimal storage capacity of networks

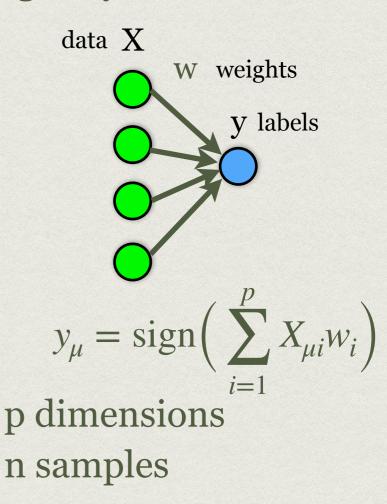
#### E Gardner and B Derrida

The Institute for Advanced Studies, The Hebrew University of Jerusalem, Jerusalem, Israel and Service de Physique Théorique de Saclay<sup>†</sup>, F-91191 Gif-sur-Yvette Cedex, France

Received 13 December 1988

Abstract. The optimal storage properties of three different neural network models are studied. For two of these models the architecture of the network is a perceptron with  $\pm J$  interactions, whereas for the third model the output can be an arbitrary function of the inputs. Analytic bounds and numerical estimates of the optimal capacities and of the minimal fraction of errors are obtained for the first two models. The third model can be solved exactly and the exact solution is compared to the bounds and to the results of numerical simulations used for the two other models.

#### Single layer neural network



high-dimensional limit

 $n \to \infty \quad p \to \infty$ 

 $n/p = \alpha = \Omega(1)$ 

#### Solved using the replica method in the high-dimensional limit

RAPID COMMUNICATIONS

PHYSICAL REVIEW A

**VOLUME 41, NUMBER 12** 

15 JUNE 1990

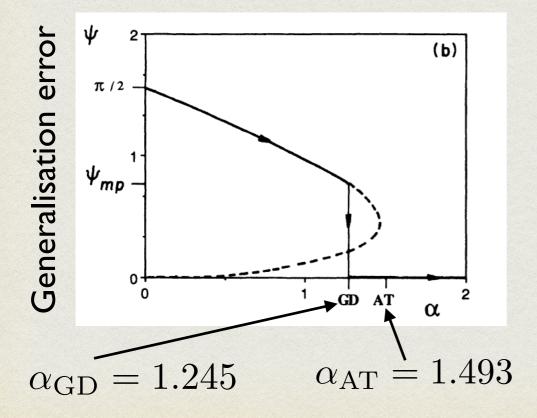
#### First-order transition to perfect generalization in a neural network with binary synapses

Géza Györgyi\*

School of Physics, Georgia Institute of Technology, Atlanta, Georgia 30332-0430

(Received 9 February 1990)

Learning from examples by a perceptron with binary synaptic parameters is studied. The examples are given by a reference (teacher) perceptron. It is shown that as the number of examples increases, the network undergoes a first-order transition, where it freezes into the state of the reference perceptron. When the transition point is approached from below, the generalization error reaches a minimal positive value, while above that point the error is constantly zero. The transition is found to occur at  $\alpha_{GD} = 1.245$  examples per coupling.



Binary teacher-weights:

$$w^* \in \{-1,1\}^p$$

 Phase transition in the generalization error's dependence on sample complexity.

 $\alpha = n/p$ 

# RECENT PROGRESS

- Solution for any activation function, general class of priors on weights.
- Rigorous proof that the replica solution for the teacher-student model is correct.
- Regions of optimality of approximate message passing algorithm.

Barbier, Krzakala, Macris, Miolane, LZ, arXiv:1708.03395, COLT'18, PNAS'19

#### CLOSED FORMULA

Def. "quenched" free energy: 
$$f = \lim_{p \to \infty} \frac{1}{p} \mathbb{E}_{y,X} \log Z(y,X)$$
  $\alpha = \frac{p}{n}$ 

#### Theorem 1:

$$f = \sup_{m} \inf_{\hat{m}} f_{RS}(m, \hat{m})$$
$$f_{RS}(m, \hat{m}) = \Phi_{P_X}(\hat{m}) + \alpha \Phi_{P_{\text{out}}}(m; \rho) - \frac{m\hat{m}}{2}$$

where

$$\begin{split} & \Phi_{P_X}(\hat{m}) \equiv \mathbb{E}_{z,x_0} \left[ \ln \mathbb{E}_x \left[ e^{\hat{m}xx_0 + \sqrt{\hat{m}}xz - \hat{m}x^2/2} \right] \right] \\ & \Phi_{P_{\text{out}}}(m;\rho) \equiv \mathbb{E}_{v,z} \left[ \int \mathrm{d}y \, P_{\text{out}}(y|\sqrt{m}\,v + \sqrt{\rho - m}\,z) \ln \mathbb{E}_w \left[ P_{\text{out}}(y|\sqrt{m}\,v + \sqrt{\rho - m}\,w) \right] \right] \\ & x, x_0 \sim P_w \qquad z, v, w \sim \mathcal{N}(0,1) \qquad \rho = \mathbb{E}_{P_w}(w^2) \end{split}$$

#### CLOSED FORMULA

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$$f = \lim_{p \to \infty} \frac{1}{p} \mathbb{E}_{y,X} \log Z(y,X)$$
  $\alpha = \frac{p}{n}$ 

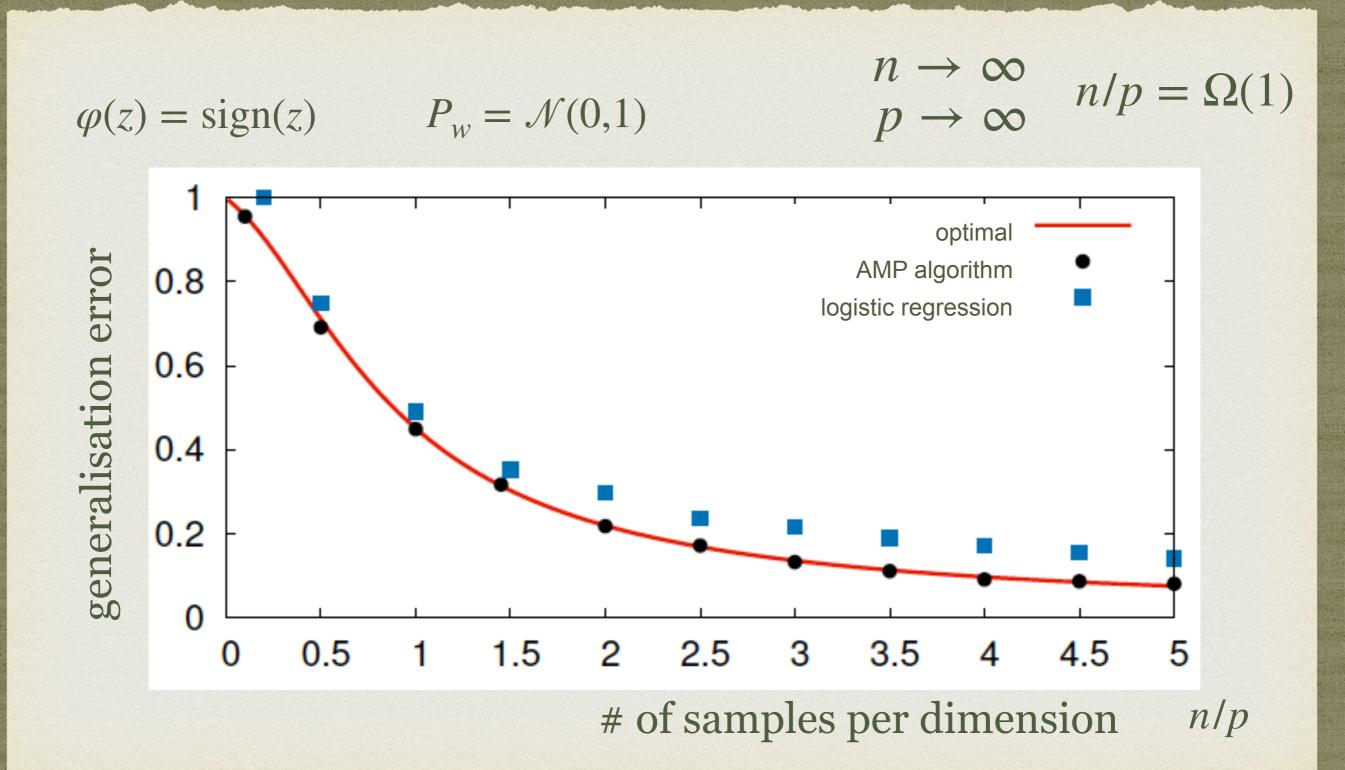
#### Theorem 1:

$$f = \sup_{m} \inf_{\hat{m}} f_{RS}(m, \hat{m})$$
  
$$f_{RS}(m, \hat{m}) = \Phi_{P_X}(\hat{m}) + \alpha \Phi_{P_{\text{out}}}(m; \rho) - \frac{m\hat{m}}{2}$$

Theorem 2: Optimal generalisation error

$$\mathcal{E}_{\mathrm{gen}} = \underset{v,\xi}{\mathbb{E}} \left[ f_{\xi}(\sqrt{\rho} \, v)^2 \right] - \underset{v}{\mathbb{E}} \underset{w,\xi}{\mathbb{E}} \left[ f_{\xi}(\sqrt{m^*} \, v + \sqrt{\rho - m^*} \, w) \right]^2$$
 where  $m^*$  is the extremizer of  $f_{\mathrm{RS}}$ . 
$$\rho = \mathbb{E}_{P_w}(w^2)$$
 
$$v, w \sim \mathcal{N}(0,1)$$
 
$$\xi \sim P_{\varepsilon}$$

# SPHERICAL PERCEPTRON



# BINARY PERCEPTRON

$$y_{\mu} = \operatorname{sign}\left(\sum_{i=1}^{p} X_{\mu i} w_{i}\right)$$
  $w_{i} \in \{-1, +1\}$  
$$p \to \infty$$
  $n/p = \Omega(1)$ 

0.8

0.6

0.4

0.2

optimal, achievable optimal
AMP algorithm logistic regression

0

0

0

0

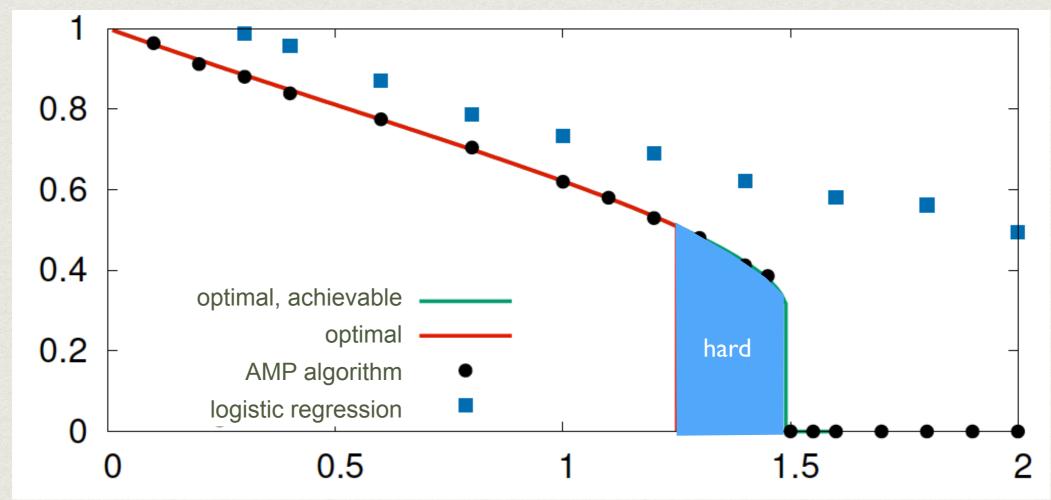
0

1.5

# of samples per dimension

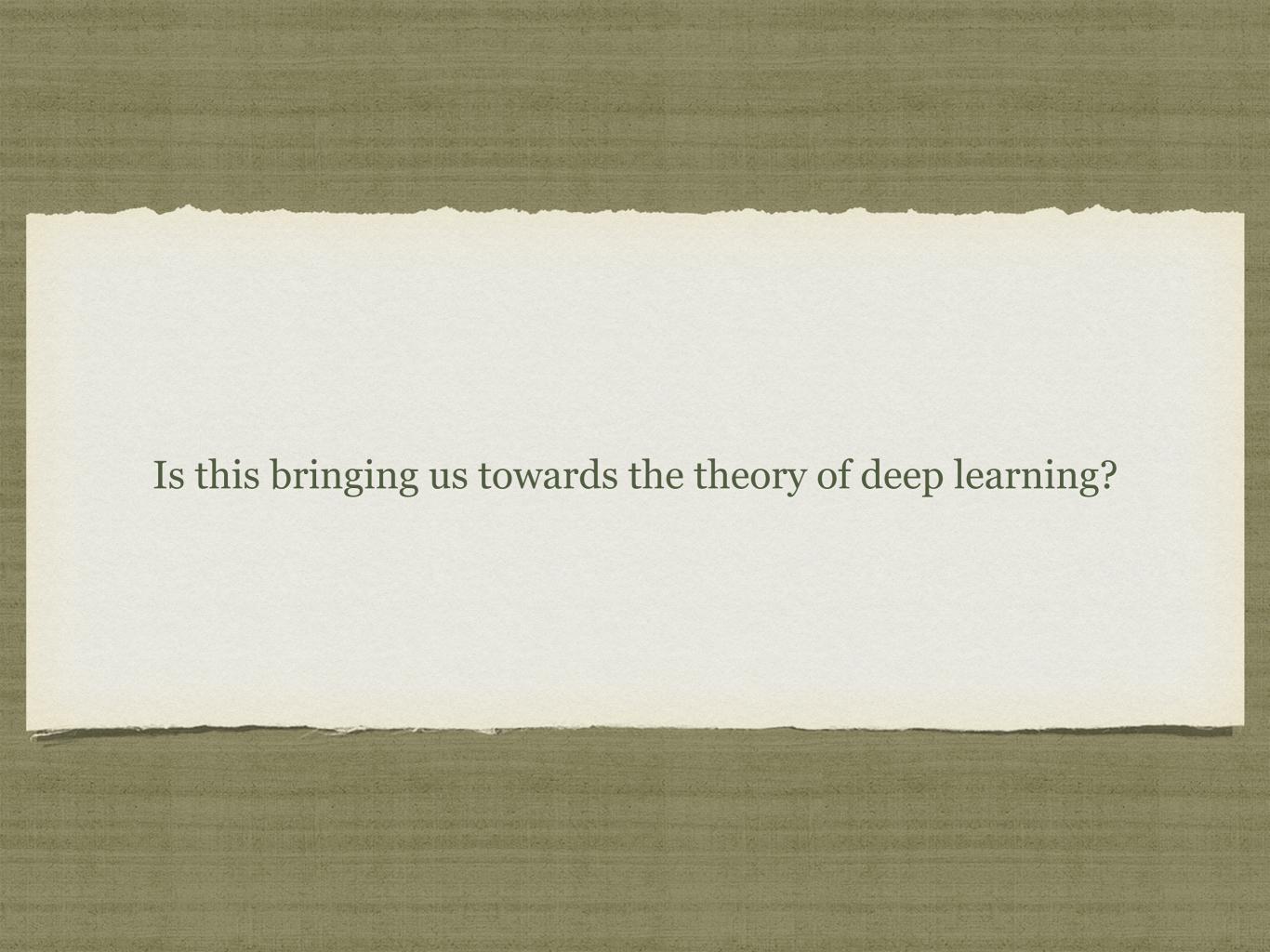
# BINARY PERCEPTRON

$$y_{\mu} = \operatorname{sign}\left(\sum_{i=1}^{p} X_{\mu i} w_{i}\right)$$
  $w_{i} \in \{-1, +1\}$   $p \to \infty$   $n/p = \Omega(1)$ 



generalisation error

# of samples per dimension

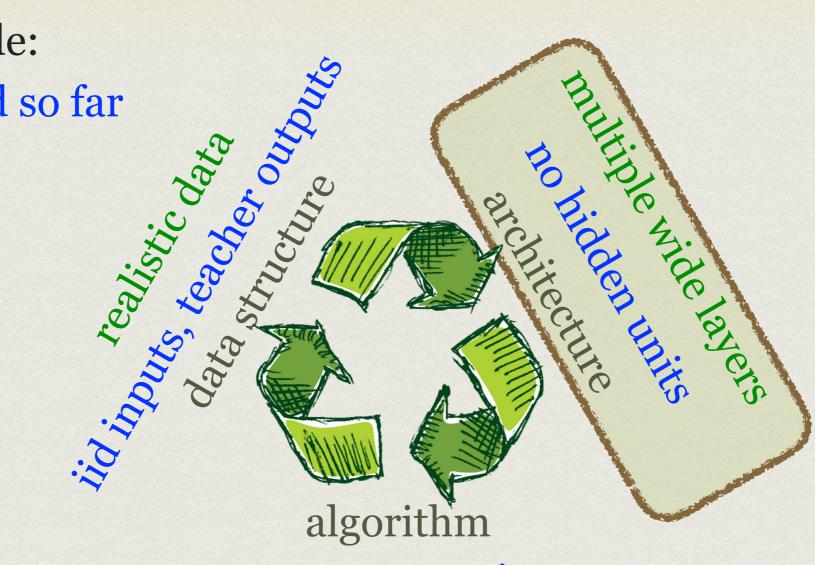


#### TOWARDS THEORY OF DEEP LEARNING?

color-code:

described so far

needed



message passing

gradient-descent-based

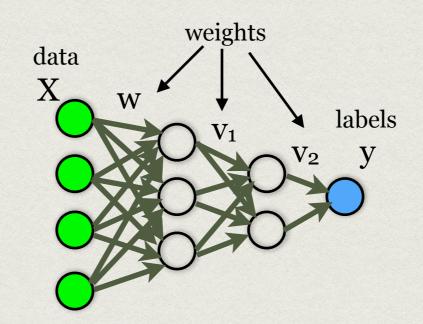
## GOING MULTI-LAYER

#### Committee machine

Model from Schwarze'92.

Proof of the replica formula, and approximate message passing Aubin, Maillard, Barbier, Macris, Krzakala, LZ, NeurIPS'18, arXiv:1806.05451.

- p input units
- O K hidden units
- output unitn training samples



L=3 layers w learned, v<sub>1</sub> & v<sub>2</sub> fixed

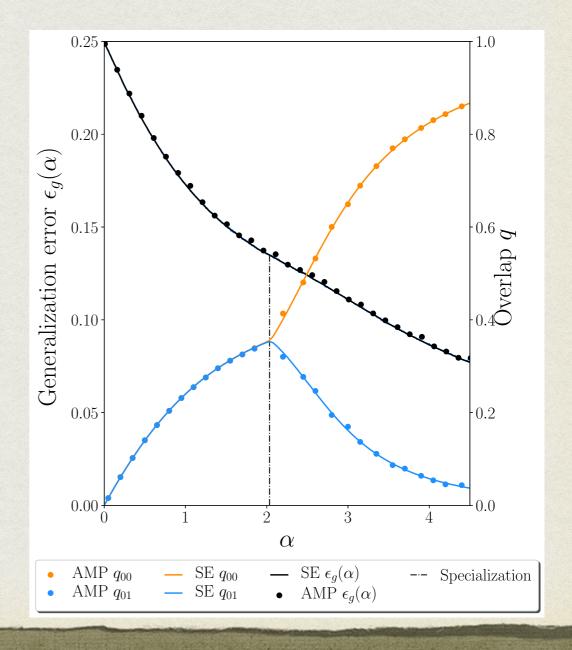
Limit: 
$$\begin{array}{ccc} n \to \infty \\ p \to \infty \end{array} \quad \alpha = n/p = \Omega(1) \qquad K = O(1)$$

# SPECIALISATION TRANSITION

hidden units K=2

$$y_{\mu} = \operatorname{sign}\left[\operatorname{sign}\left(\sum_{i} X_{\mu,i} w_{i,1}\right) + \operatorname{sign}\sum_{i} \left(X_{\mu,i} w_{i,2}\right)\right]$$

- Specialization phase transition
   hidden units specialise to
   correlate with specific features.
- Consequence: Sharp threshold for number of samples below which linear regression is the best thing to do.

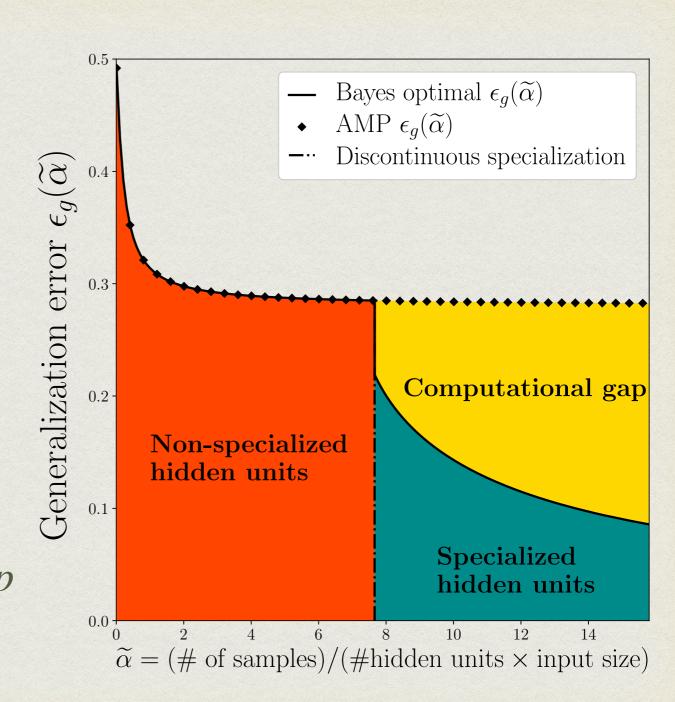


# COMPUTATIONAL GAP

$$y_{\mu} = \operatorname{sign}\left[\sum_{a=1}^{K} \operatorname{sign}\left(\sum_{i} X_{\mu,i} w_{i,a}\right)\right]$$

hidden units  $K\gg 1$ 

- Large algorithmic gap:
  - ▶ IT threshold: n > 7.65Kp
  - Algorithmic threshold  $n > \text{const. } K^2 p$



#### TOWARDS THEORY OF DEEP LEARNING?

in to the teath of color-code: only few hidden units
only few hidden units described so far needed algorithm message passing gradient-descent-based

## GRADIENT-BASED ALGORITHMS

spherical constraint 
$$\langle \eta_i(t)\eta_j(t')\rangle = 2T\delta_{ij}\delta(t-t')$$
 (weight decay) noise  $\dot{x}_i(t) = -\mu(t)x_i(t) - \frac{\partial \mathcal{H}}{\partial x_i} + \eta_i(t)$  gradient

- T=1 Langevin algorithm: At large time (exponentially) samples the posterior measure.
- T=o Gradient flow.

Where do they go in large constant time?

#### MIXED SPIKED MATRIX-TENSOR MODEL

• On the same signal x\* observe a matrix Y and tensor T as:

$$Y_{ij} = \frac{1}{\sqrt{N}} x_i^* x_j^* + \xi_{ij} \qquad \xi_{ij} \sim \mathcal{N}(0, \Delta_2)$$

$$T_{i_1 \dots i_p} = \frac{\sqrt{(p-1)!}}{N^{(p-1)/2}} x_{i_1}^* \dots x_{i_p}^* + \xi_{i_1 \dots i_p} \qquad \xi_{i_1, \dots, i_p} \sim \mathcal{N}(0, \Delta_p)$$

Corresponding Hamiltonian (loss function, log-likelihood)

$$\mathcal{H}(x) = -\frac{1}{\Delta_2 \sqrt{N}} \sum_{i < j} Y_{ij} x_i x_j - \frac{\sqrt{(p-1)!}}{\Delta_p N^{(p-1)/2}} \sum_{i_1 < \dots < i_p} T_{i_1 \dots i_p} x_{i_1} \dots x_{i_p}$$
spherical constraint: 
$$\sum_{i=1}^{N} x_i^2 = N$$

Spiked version of the mixed 2+p spherical spin glass model.

#### DYNAMICAL MEAN FIELD THEORY

The same model without spike: mixed spherical p-spin glass Mean field theory of glassy dynamics:

VOLUME 71, NUMBER 1

PHYSICAL REVIEW LETTERS

5 JULY 1993

#### Analytical Solution of the Off-Equilibrium Dynamics of a Long-Range Spin-Glass Model

L. F. Cugliandolo and J. Kurchan

Dipartimento di Fisica, Università di Roma, La Sapienza, I-00185 Roma, Italy
and Istituto Nazionale di Fisica Nucleare, Sezione di Roma I, Roma, Italy

(Received 8 March 1993)

We study the nonequilibrium relaxation of the spherical spin-glass model with p-spin interactions in the  $N \to \infty$  limit. We analytically solve the asymptotics of the magnetization and the correlation and response functions for long but finite times. Even in the thermodynamic limit the system exhibits "weak" (as well as "true") ergodicity breaking and aging effects. We determine a functional Parisi-like order parameter  $P_d(q)$  which plays a similar role for the dynamics to that played by the usual function for the statics.

PACS numbers: 75.10.Nr, 02.50.-r, 05.40.+j, 64.60.Cn

Proof of this without spike: BenArous, Dembo, Guionnet'06.

## LANGEVIN STATE EVOLUTION

Sarao, Biroli, Cammarota, Krzakala, Urbani, LZ, arXiv:1812.09066.

$$C_N(t,t') \equiv \frac{1}{N} \sum_{i=1}^N x_i(t) x_i(t') ,$$

$$\overline{C}_N(t) \equiv \frac{1}{N} \sum_{i=1}^N x_i(t) x_i^* ,$$

$$R_N(t,t') \equiv \frac{1}{N} \sum_{i=1}^N \partial x_i(t) / \partial h_i(t') |_{h_i=0} ,$$

$$Q(x) = x^2/(2\Delta_2) + x^p/(p\Delta_p).$$

$$N \to \infty$$

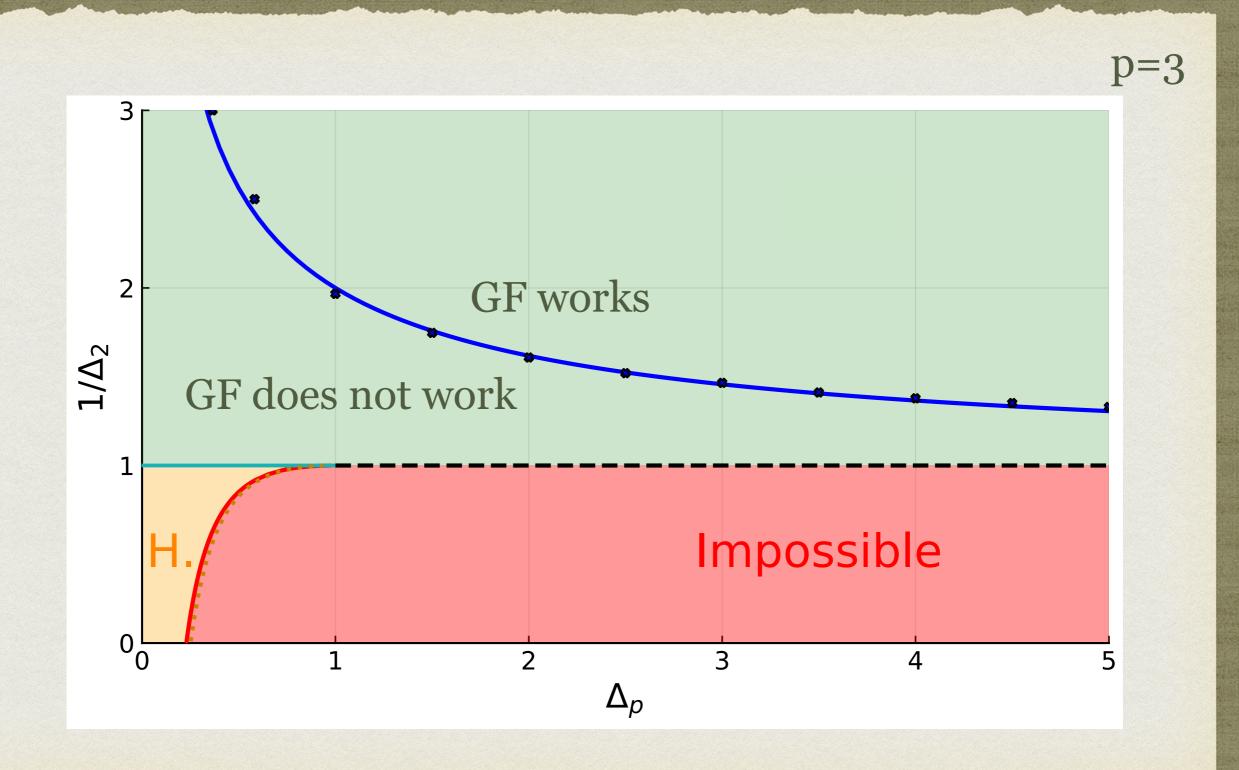
$$\frac{\partial}{\partial t}C(t,t') = 2R(t',t) - \mu(t)C(t,t') + Q'(\overline{C}(t))\overline{C}(t') + \int_0^t dt''R(t,t'')Q''(C(t,t''))C(t',t'') + \int_0^{t'} dt''R(t',t'')Q'(C(t,t'')),$$

$$\frac{\partial}{\partial t}R(t,t') = \delta(t-t') - \mu(t)R(t,t') + \int_{t'}^t dt''R(t,t'')Q''(C(t,t''))R(t'',t'),$$

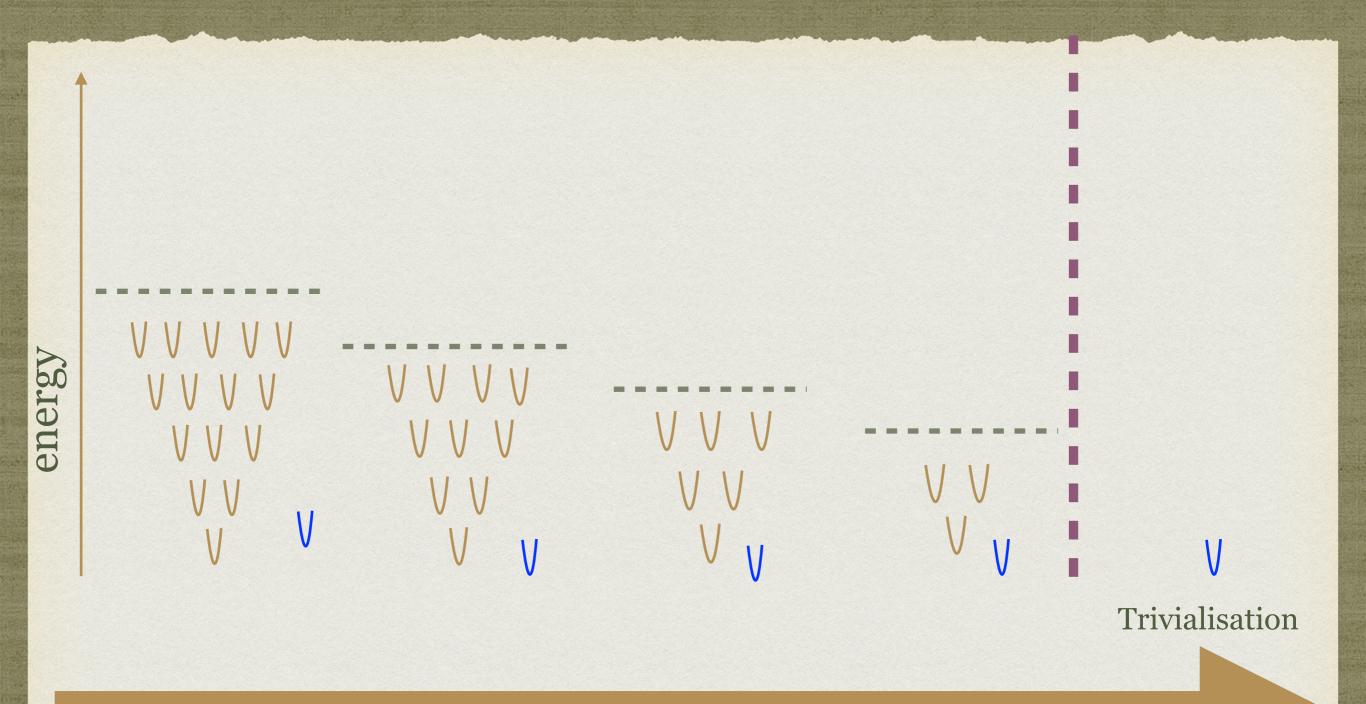
$$\frac{\partial}{\partial t}\overline{C}(t) = -\mu(t)\overline{C}(t) + Q'(\overline{C}(t)) + \int_0^t dt''R(t,t'')\overline{C}(t'')Q''(C(t,t'')),$$
Langevin algorithm (T=1)

$$\begin{split} &\frac{\partial}{\partial t}C(t,t') = -\tilde{\mu}(t)C(t,t') + Q'(\overline{C}(t))\overline{C}(t') &\quad + \int_0^t dt'' R(t,t'')Q''(C(t,t''))C(t',t'') &\quad + \int_0^{t'} dt'' R(t',t'')Q'(C(t,t'')), \\ &\frac{\partial}{\partial t}R(t,t') = -\tilde{\mu}(t)R(t,t') + \int_{t'}^t dt'' R(t,t'')Q''(C(t,t''))R(t'',t'), \\ &\frac{\partial}{\partial t}\overline{C}(t) = -\tilde{\mu}(t)\overline{C}(t) + Q'(\overline{C}(t)) &\quad + \int_0^t dt'' R(t,t'')\overline{C}(t'')Q''(C(t,t'')), \end{split}$$
 Gradient flow (T=o)

## GRADIENT-FLOW PHASE DIAGRAM



# POPULAR "EXPLANATION"



Increasing the SNR

## COUNTING MINIMA: KAC-RICE

Sarao, Biroli, Cammarota, Krzakala, Urbani, LZ'19

#### Annealed entropy of local minima (at m=0 also quenched):

$$\tilde{\Sigma}_{\Delta_{2},\Delta_{p}}(m,\epsilon_{2},\epsilon_{p}) = \frac{1}{2} \log \frac{\frac{p-1}{\Delta_{p}} + \frac{1}{\Delta_{2}}}{\frac{1}{\Delta_{p}} + \frac{1}{\Delta_{2}}} + \frac{1}{2} \log(1 - m^{2})$$

$$- \frac{1}{2} \frac{\left(\frac{m^{p-1}}{\Delta_{p}} + \frac{m}{\Delta_{2}}\right)^{2}}{\frac{1}{\Delta_{p}} + \frac{1}{\Delta_{2}}} (1 - m^{2}) - \frac{p\Delta_{p}}{2} \left(\epsilon_{p} + \frac{m^{p}}{p\Delta_{p}}\right)^{2}$$

$$- \Delta_{2} \left(\epsilon_{2} + \frac{m^{2}}{2\Delta_{2}}\right)^{2} + \Phi(t) - L(\theta, t),$$

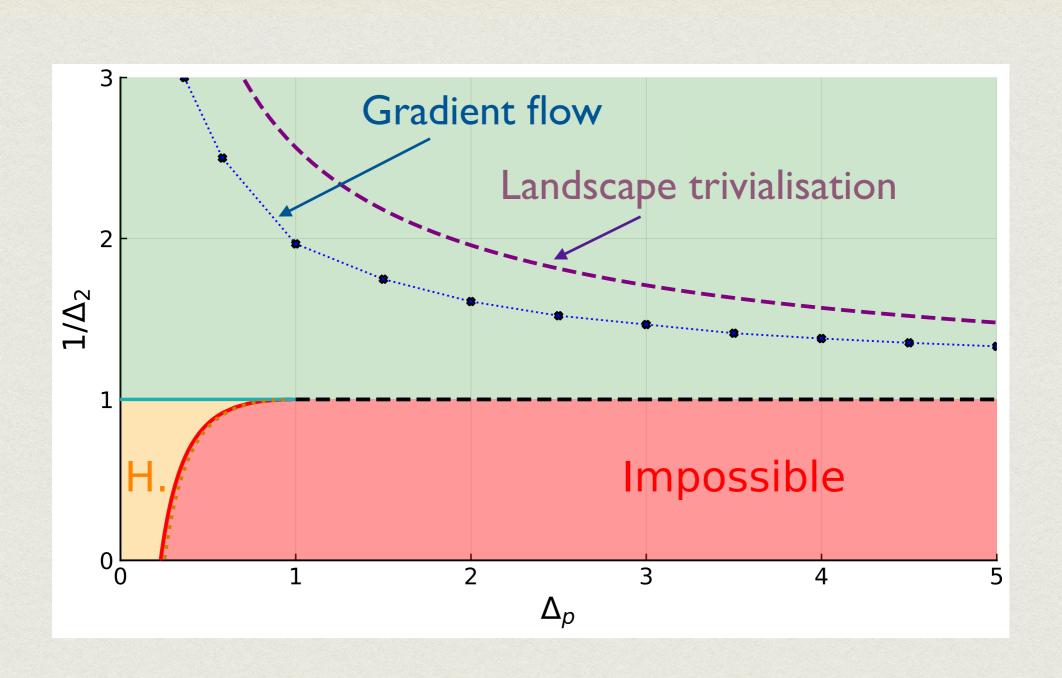
Similar to Ben Arous, Mei, Song, Montanari, Nica'17; Ros, Ben Arous, Biroli, Cammarota'18 for spiked tensor model

#### where:

$$\Phi(t) = \frac{t^2}{4} + \mathbb{1}_{|t| > 2} \left[ \log \left( \sqrt{\frac{t^2}{4} - 1} + \frac{|t|}{2} \right) - \frac{|t|}{4} \sqrt{t^2 - 4} \right]$$

$$L(\theta,t) = \begin{cases} &\frac{1}{4} \int_{\theta+\frac{1}{\theta}}^{t} \sqrt{y^2 - 4} dy - \frac{\theta}{2} \left( t - \left( \theta + \frac{1}{\theta} \right) \right) \\ &+ \frac{t^2 - \left( \theta + \frac{1}{\theta} \right)^2}{8} & \theta > 1, \ 2 \le t < \frac{\theta^2 + 1}{\theta} \\ &\infty & t < 2 \\ &0 & \text{otherwise.} \end{cases}$$

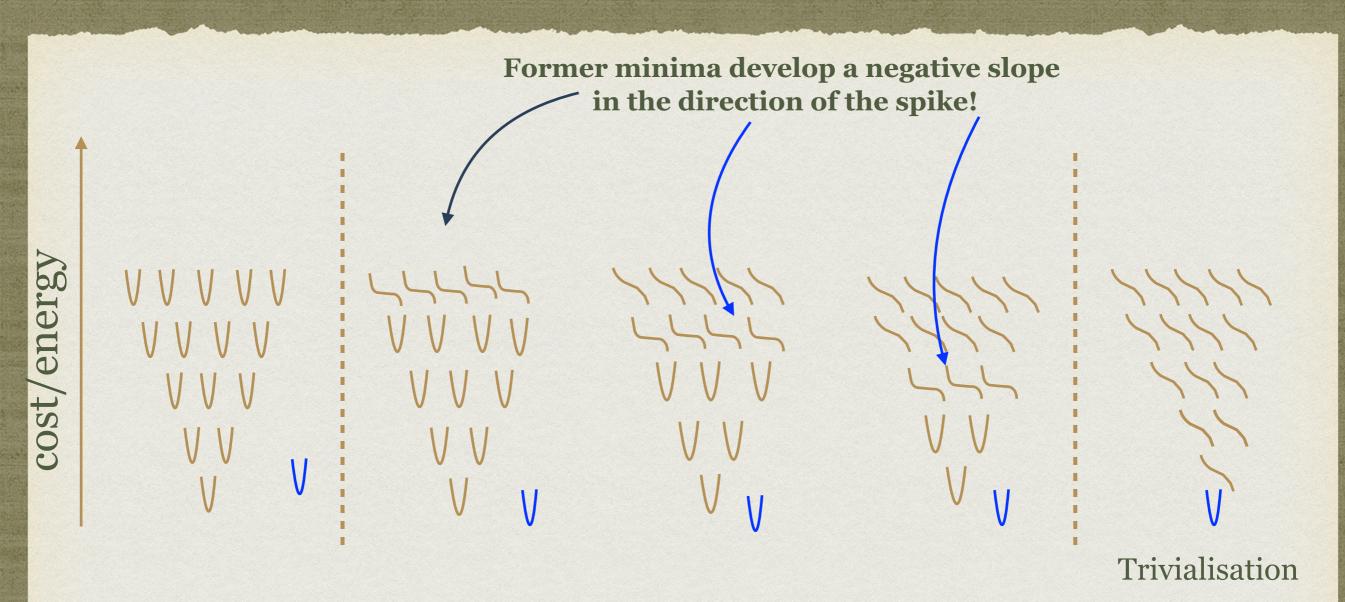
# WHAT IS GOING ON?



p=3

# LANDSCAPE ANALYSIS

Sarao, Biroli, Cammarota, Krzakala, Urbani, LZ; NeurIPS'19, arXiv:1907.08226.



Increasing the SNR

## THRESHOLD RECIPE

Dynamics first goes to the threshold states (replicon condition):

$$\frac{T^2}{(1-q^{\text{th}})^2} = (p-1)\frac{(q^{\text{th}})^{p-2}}{\Delta_p} + \frac{1}{\Delta_2}$$

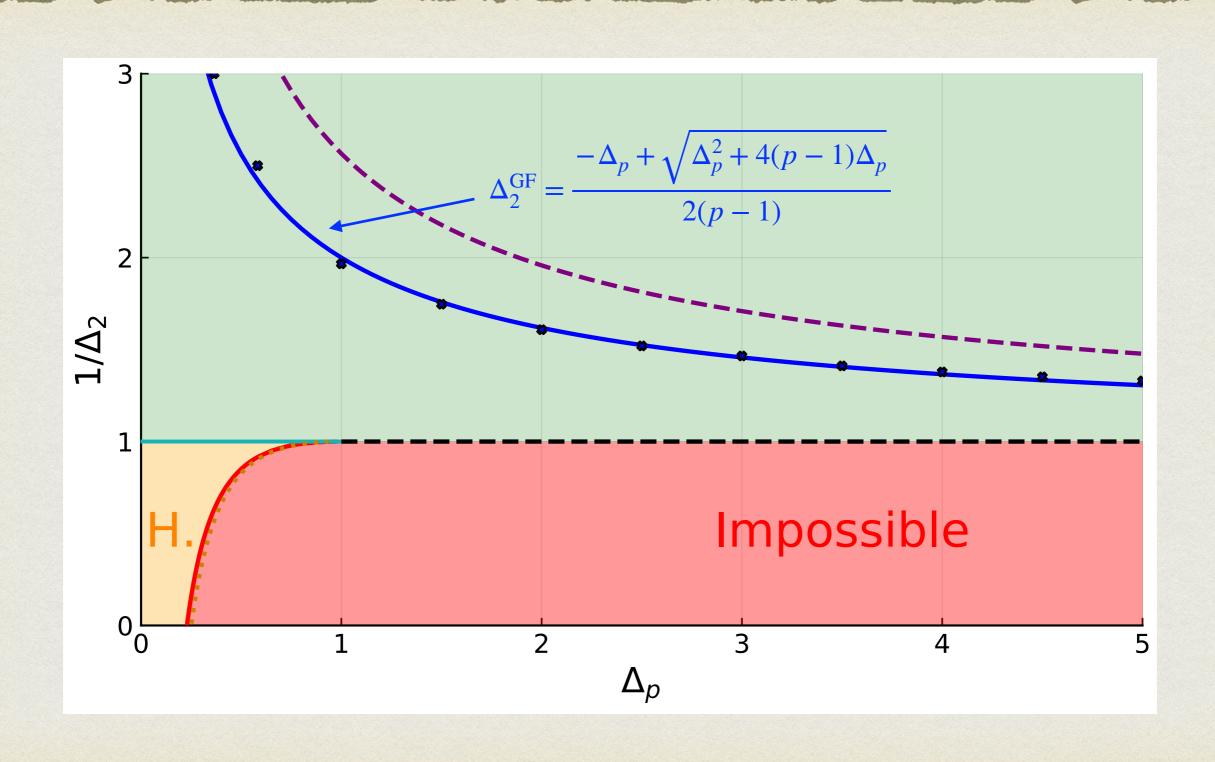
AMP state evolution at fixed q, determines stability of T=0:

$$m^{t+1} = \frac{1-q}{T} \left( \frac{m^t}{\Delta_2} + \frac{(m^t)^{p-2}}{\Delta_p} \right)$$

Putting together gives the Langevin/gradient-flow threshold:

$$\frac{1}{\Delta_2^2} = (p-1)\frac{(1-T\Delta_2)^{p-2}}{\Delta_p} + \frac{1}{\Delta_2}$$

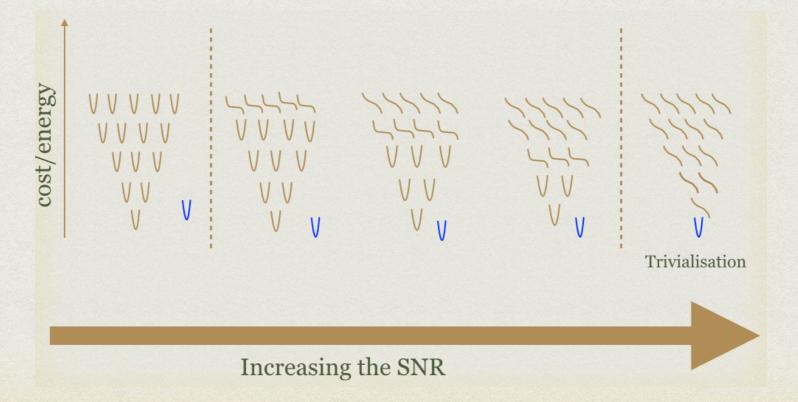
### GRADIENT-FLOW PHASE DIAGRAM



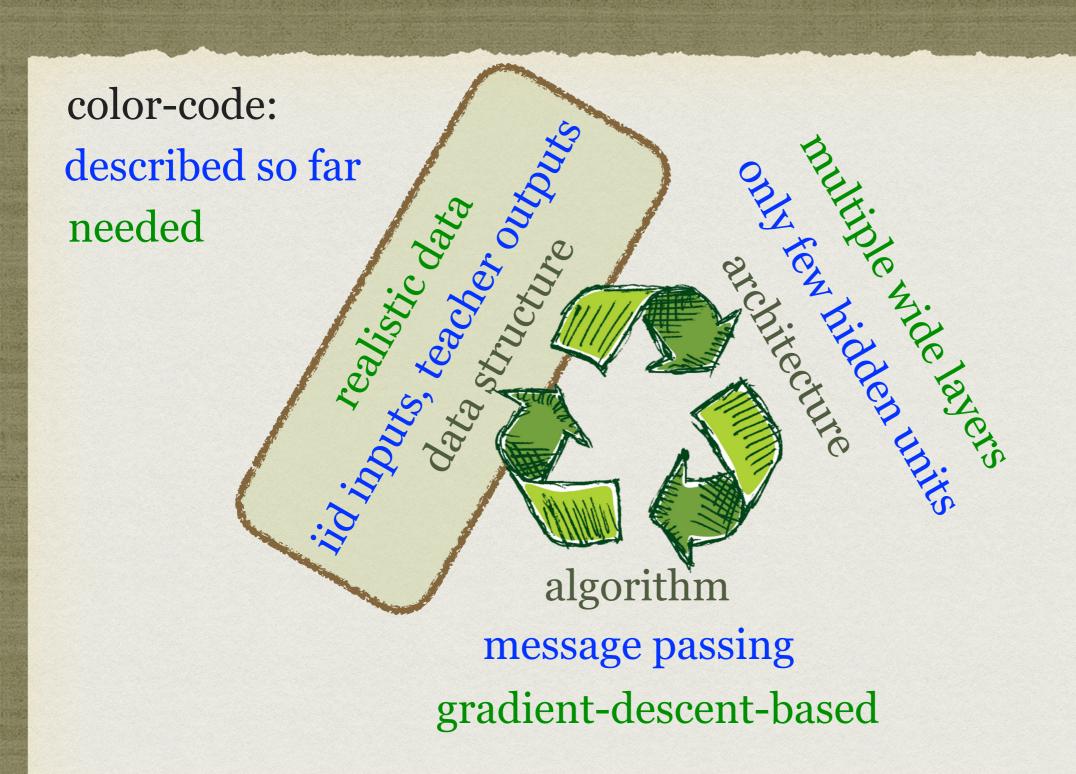
### CONCLUSION ON GRADIENT FLOW

- Gradient flow (sometimes) works even when spurious local minima are present. Quantified with the Kac-Rice approach.
- First time we have a closed-form conjecture for the threshold of gradient-based algorithms including constants.

  Applicable beyond the presented model?



#### TOWARDS THEORY OF DEEP LEARNING?



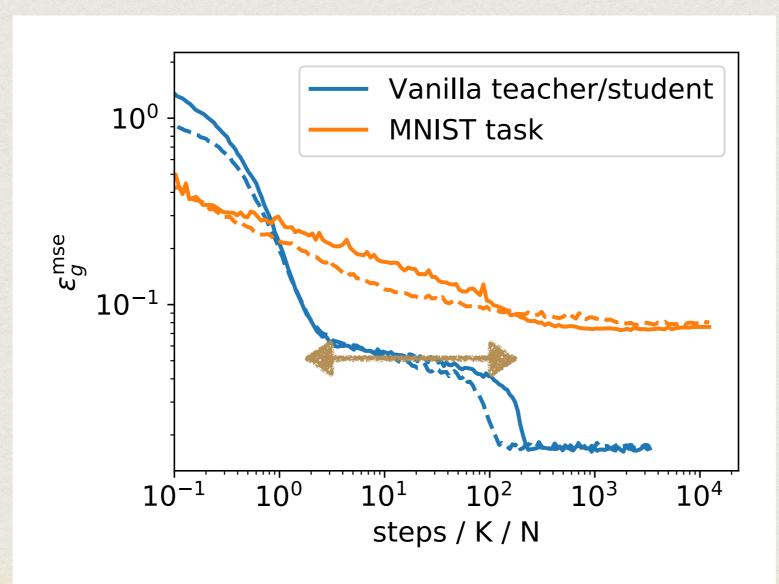
## MNIST VS TEACHER/STUDENT

Goldt, Krzakala, Mézard, LZ; arXiv:1909.11500

Teacher/student:

Plateau in learning dynamics, due to specialisation (Saad, Solla'95).

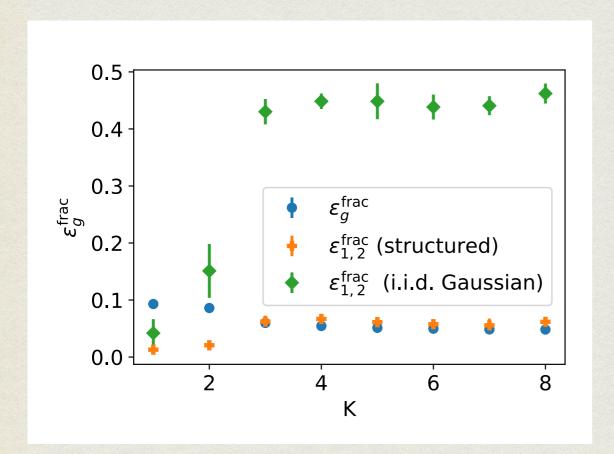
MNIST (even vs odd classification): No plateau ...



## MNIST VS TEACHER/STUDENT

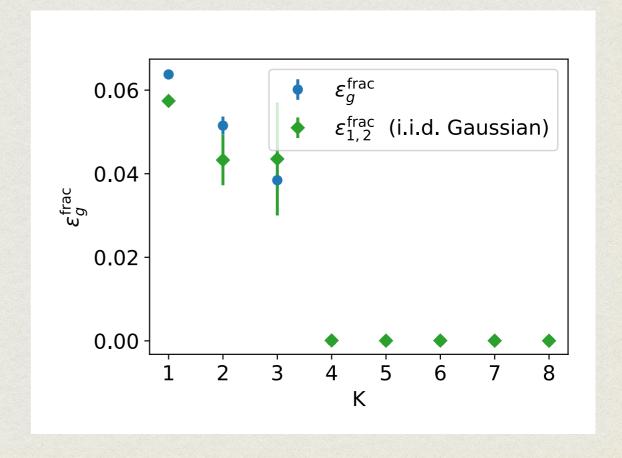
MNIST (odd vs even):

Two independent students do not learn the same function!



Teacher/student:

Two independent students learn the same function!



## HIDDEN MANIFOLD MODEL

Input data:

$$X \in \mathbb{R}^{n \times p}$$

$$C \in \mathbb{R}^{n \times d}$$
$$F \in \mathbb{R}^{d \times p}$$

n samples, p input & d latent dimension.

Input on low-dimensional manifold.

$$X = f(CF)$$

C, F iid matrices.

True labels:

Depend on the latent coordinates C.

$$\tilde{y}_{\mu} = \sum_{m=1}^{M} \tilde{v}_{m} g\left(\langle \tilde{\mathbf{w}}_{m}, \mathbf{C}_{\mu} \rangle\right)$$

Vanilla teacher/student

X is iid matrix

$$y_{\mu} = \sum_{m=1}^{M} v_m g\left(\langle \mathbf{w}_m, \mathbf{X}_{\mu} \rangle\right)$$

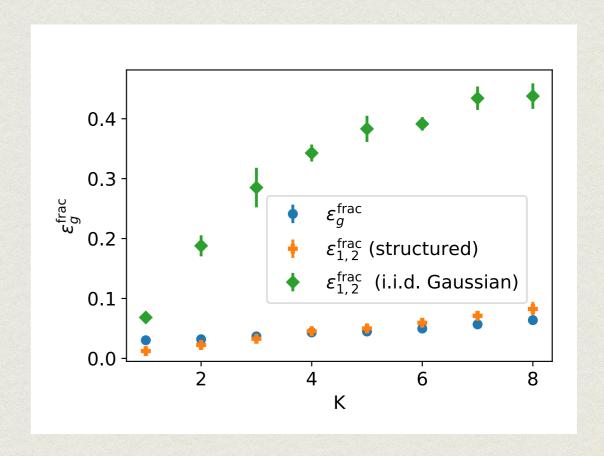
### MNIST VS HIDDEN MANIFOLD

MNIST (odd vs even):

Two independent students do not learn the same function!

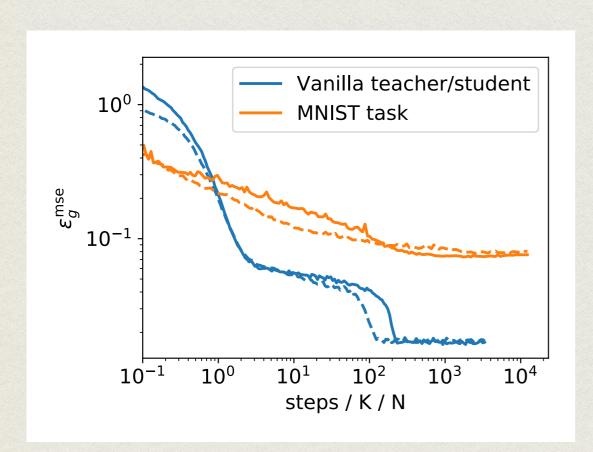
0.5 0.4 0.3 0.2 0.1 0.0 0.1 0.0 0.0 0.1 0.0 0.0 0.1 0.0

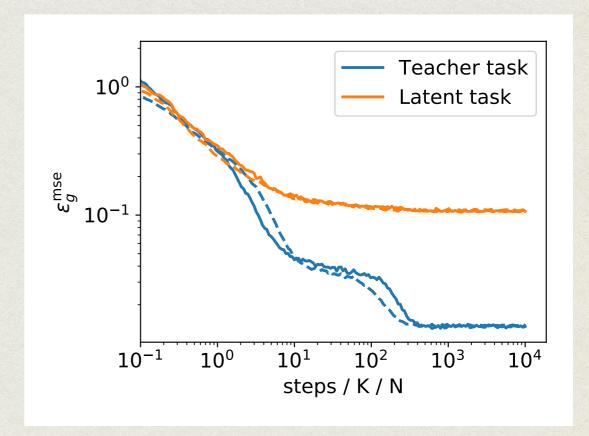
Hidden manifold (d=10)
Two independent students do
not learn the same function!



### MNIST VS HIDDEN MANIFOLD

Teacher acting on X: Plateau in learning dynamics MNIST & hidden manifold: No plateau ...





#### CONCLUSION ON HIDDEN MANIFOLD

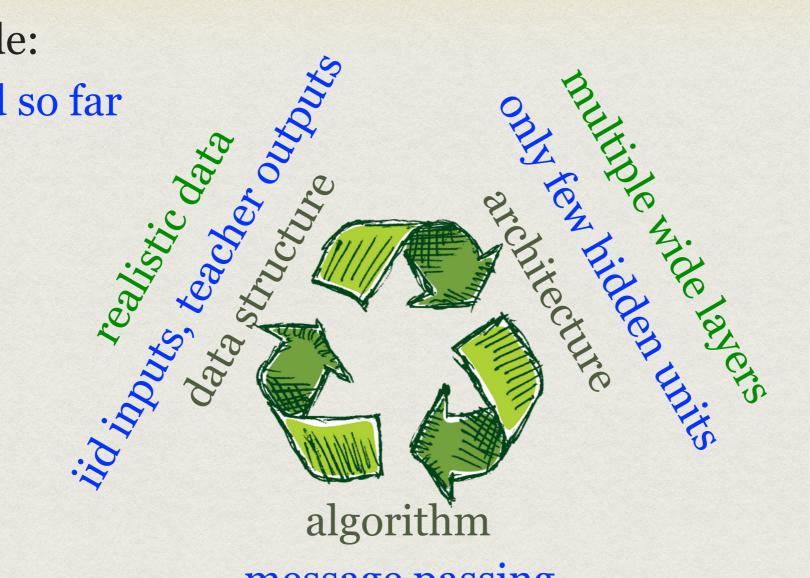
- The hidden manifold model reproduces/captures behaviour of learning-dynamics on MNIST.
- Both (i) low-dimensional structure of input, and (ii) labels depending on the latent representation are needed.
- TODO: Solve analytically.
- TODO: Generalize to be able to demonstrate the advantage of depth.

#### TOWARDS THEORY OF DEEP LEARNING?

color-code:

described so far

needed



message passing

gradient-descent-based

#### REFERENCES FOR THIS TALK



- Barbier, Krzakala, Macris, Miolane, LZ; Optimal errors and phase transitions in high-dimensional generalized linear models; COLT'18, PNAS'19, arXiv:1708.03395.
- Aubin, Maillard, Barbier, Macris, Krzakala, LZ; *The committee machine: Computational to statistical gaps in learning a two-layers neural network*, spotlight at NeurIPS'18, arXiv:1806.05451.
- Sarao, Biroli, Cammarota, Krzakala, Urbani, LZ; Marvels and Pitfalls of the Langevin Algorithm in Noisy High-dimensional Inference, arXiv:1812.09066.
- Sarao, Krzakala, Urbani, LZ; Passed & Spurious: Descent Algorithms and Local Minima in Spiked Matrix-Tensor Models; ICML'19, arXiv:1902.00139.
- Sarao, Biroli, Cammarota, Krzakala, Urbani, LZ; Who is Afraid of Big Bad Minima? Analysis of Gradient-Flow in a Spiked Matrix-Tensor Model; spotlight at NeurIPS'19, arXiv:1907.08226.
- Goldt, Krzakala, Mézard, LZ; Modelling the influence of data structure on learning in neural networks; arXiv:1909.11500.
- Of independent interest: *Machine learning and the physical sciences*; Carleo, Cirac, Cranmer, Daudet, Schuld, Tishby, Vogt-Maranto, LZ; arXiv:1903.10563